

An octonionic formulation of the M-theory algebra

A. Anastasiou, L. Borsten, M.J. Duff, L.J. Hughes and S. Nagy

*Theoretical Physics, Blackett Laboratory, Imperial College London,
London SW7 2AZ, United Kingdom*

E-mail: alexandros.anastasiou07@imperial.ac.uk,
leron.borsten@imperial.ac.uk, m.duff@imperial.ac.uk,
leo.hughes07@imperial.ac.uk, s.nagy11@imperial.ac.uk

ABSTRACT: We give an octonionic formulation of the $\mathcal{N} = 1$ supersymmetry algebra in $D = 11$, including all brane charges. We write this in terms of a novel outer product, which takes a pair of elements of the division algebra \mathbb{A} and returns a real linear operator on \mathbb{A} . More generally, with this product comes the power to rewrite any linear operation on \mathbb{R}^n ($n = 1, 2, 4, 8$) in terms of multiplication in the n -dimensional division algebra \mathbb{A} . Finally, we consider the reinterpretation of the $D = 11$ supersymmetry algebra as an octonionic algebra in $D = 4$ and the truncation to division subalgebras.

KEYWORDS: Extended Supersymmetry, M-Theory

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1 Introduction

A recurring theme in the study of supersymmetry and string theory is the connection to the four division algebras: the real numbers \mathbb{R} , the complex numbers \mathbb{C} , the quaternions \mathbb{H} and the octonions \mathbb{O} . See, for example, [1–9]. The octonions are of particular interest in this context since they may be used to describe representations of the Lorentz group in spacetime dimensions $D = 10, 11$, where string and M-theory live. Furthermore, the octonions provide a natural explanation [10, 11] for the appearance of exceptional groups as the U-dualities of supergravities [12] and M-theory [13, 14].

A $D = 11$ spinor with 32 components may be packaged as a 4-component octonionic column vector [6, 15]. This has prompted the question of how to write the algebra of $D = 11$ supergravity (or ‘M-algebra’) using octonionic supercharges Q . This was explored in [15] where the problem was highlighted that the apparently natural choice of octonionic matrices could not provide enough degrees of freedom to account for all of M-theory’s brane charges. Another fundamental question that arises when writing the $\{Q, Q\}$ algebra in this way is whether or not the usual anti-commutator is really the appropriate object to study, given that the fermionic supercharges are written over a non-commutative and non-associative algebra \mathbb{O} .

In the present paper we tackle this problem by introducing a novel outer product, which takes a pair of elements belonging to a division algebra \mathbb{A} and returns a real linear operator on \mathbb{A} , expressed using multiplication in \mathbb{A} . This product enables one to rewrite any expression involving $n \times n$ matrices and n -dimensional vectors in terms of multiplication in the n -dimensional division algebra \mathbb{A} . We solve the problem of the octonionic M-algebra using this product, which allows a derivation of the correct $\{Q, Q\}$ bracket. In the final section we consider “Cayley-Dickson halving” the octonionic M-algebra, which corresponds to its reinterpretation as the maximal supergravity algebra in $D = 7, 5, 4$. For example, the M-algebra may be considered to be an octonionic rewriting of the $D = 4$, $\mathcal{N} = 8$

supersymmetry algebra; from this perspective the $D = 4$, $\mathcal{N} = 1$ algebra comes from a truncation $\mathcal{O} \rightarrow \mathbb{R}$.

2 The division algebras

A normed division algebra is an algebra \mathbb{A} equipped with a positive-definite norm satisfying the condition

$$\|xy\| = \|x\|\|y\|. \quad (2.1)$$

Remarkably, there are only four such algebras: \mathbb{R} , \mathbb{C} , \mathbb{H} and \mathbb{O} , with dimensions $n = 1, 2, 4$ and 8 , respectively.

A division algebra element $x \in \mathbb{A}$ is written as the linear combination of n basis elements with real coefficients: $x = x_a e_a$, with $x_a \in \mathbb{R}$ and $a = 0, \dots, (n-1)$. One basis element $e_0 = 1$ is real; the other $(n-1)$ basis elements e_i are imaginary:

$$e_0^2 = 1, \quad e_i^2 = -1, \quad (2.2)$$

where $i = 1, \dots, (n-1)$. In analogy with the complex case, we define a conjugation operation indicated by $*$, which changes the sign of the imaginary basis elements:

$$e_0^* = e_0, \quad e_i^* = -e_i. \quad (2.3)$$

The multiplication rule for the basis elements of a division algebra is given by:

$$\begin{aligned} e_a e_b &= (\delta_{a0} \delta_{bc} + \delta_{0b} \delta_{ac} - \delta_{ab} \delta_{0c} + C_{abc}) e_c \equiv \Gamma_{bc}^a e_c, \\ e_a^* e_b &= (\delta_{a0} \delta_{bc} - \delta_{0b} \delta_{ac} + \delta_{ab} \delta_{0c} - C_{abc}) e_c \equiv \bar{\Gamma}_{bc}^a e_c, \end{aligned} \quad (2.4)$$

where we define the structure constants¹

$$\begin{aligned} \Gamma_{bc}^a &= \delta_{a0} \delta_{bc} + \delta_{b0} \delta_{ac} - \delta_{ab} \delta_{c0} + C_{abc}, \\ \bar{\Gamma}_{bc}^a &= \delta_{a0} \delta_{bc} - \delta_{b0} \delta_{ac} + \delta_{ab} \delta_{c0} - C_{abc} \Rightarrow \Gamma_{bc}^a = \bar{\Gamma}_{cb}^a. \end{aligned} \quad (2.5)$$

The tensor C_{abc} is totally antisymmetric with $C_{0ab} = 0$, so it is identically zero for $\mathbb{A} = \mathbb{R}, \mathbb{C}$. For the quaternions C_{ijk} is simply the permutation symbol ε_{ijk} , while for the octonions the non-zero C_{ijk} are specified by the set of oriented lines of the Fano plane, see [16].

One of the most important properties of the division algebras is that they provide a representation of the $\text{SO}(n)$ Clifford algebra. This is reflected in the structure constants, which satisfy

$$\begin{aligned} \Gamma^a \bar{\Gamma}^b + \Gamma^b \bar{\Gamma}^a &= 2\delta^{ab} \mathbb{1}, \\ \bar{\Gamma}^a \Gamma^b + \bar{\Gamma}^b \Gamma^a &= 2\delta^{ab} \mathbb{1}. \end{aligned} \quad (2.6)$$

In other words, we have the interpretation that multiplying a division algebra element ψ by the basis element e_a has the effect of multiplying ψ 's components by the gamma matrix $\bar{\Gamma}^a$:

$$e_a \psi = e_a e_b \psi_b = \Gamma_{bc}^a e_c \psi_b = e_c \bar{\Gamma}_{cb}^a \psi_b. \quad (2.7)$$

¹The unusual choice of index structure is for later convenience - see equations (2.6) and (2.7).

This property is essential for many of the applications of division algebras to physics, including that of this paper.

A natural inner product [16] on \mathbb{A} is given by:

$$\langle x|y \rangle = \frac{1}{2} (x^* y + y^* x) = x_a y_a \quad \text{i.e.} \quad \langle e_a|e_b \rangle = \delta_{ab}. \quad (2.8)$$

This is just the canonical inner product on \mathbb{R}^n .

3 A new outer product

It is interesting to see what other linear operations on \mathbb{R}^n look like when written in terms of the division-algebraic multiplication rule. This was explored in [17], but we take a different approach here. Consider the following general problem. Given some linear operator on \mathbb{R}^n expressed as an $n \times n$ matrix M_{ab} , we would like to find an operator \hat{M} on the division algebra \mathbb{A} such that \hat{M} has the effect of multiplying the components of $x = x_a e_a \in \mathbb{A}$ by M_{ab} :

$$\hat{M}x \equiv e_a M_{ab} x_b. \quad (3.1)$$

An explicit form for this operator can be found using the inner product above. First we rewrite

$$\begin{aligned} M_{ab} &= M_{cd} \langle e_a|e_c \rangle \langle e_b|e_d \rangle \\ &= \frac{1}{2} M_{cd} \langle e_a|e_c (e_d^* e_b) + e_c (e_b^* e_d) \rangle. \end{aligned} \quad (3.2)$$

Now it is clear that the operator

$$\hat{M} \equiv \frac{1}{2} M_{cd} \left(e_c (e_d^* \cdot) + e_c ((\cdot)^* e_d) \right), \quad (3.3)$$

where a dot represents a slot for an octonion, has matrix elements

$$\langle e_a|\hat{M}e_b \rangle = M_{ab}. \quad (3.4)$$

This suggests that we write the outer product for division algebra elements using their multiplication rule, defining:

$$\begin{aligned} \times : \mathbb{A} \otimes \mathbb{A} &\rightarrow \text{End}(\mathbb{A}) \\ e_a \otimes e_b &\mapsto e_a \times e_b \equiv \frac{1}{2} \left(e_a (e_b^* \cdot) + e_a ((\cdot)^* e_b) \right). \end{aligned} \quad (3.5)$$

With the new product comes the power to rewrite any expression involving $n \times n$ matrices and n -dimensional vectors in terms of multiplication in the n -dimensional division algebra \mathbb{A} .

It is useful to note various equivalent ways of writing the outer product above:

$$\begin{aligned} e_a \times e_b &= \frac{1}{2} \left(e_a (e_b^* \cdot) + e_a ((\cdot)^* e_b) \right) \\ &= \frac{1}{2} \left((\cdot e_b^*) e_a + (e_b (\cdot)^*) e_a \right) \\ &= \frac{1}{2} \left(e_a (e_b (\cdot)^*) + e_a (\cdot e_b^*) \right) \\ &= \frac{1}{2} \left(((\cdot)^* e_b) e_a + (e_b^* \cdot) e_a \right). \end{aligned} \quad (3.6)$$

Due to the alternativity of the division algebras we also have

$$e_a(e_b^* \cdot) + e_a((\cdot)^* e_b) = (e_a e_b^*)(\cdot) + (e_a(\cdot)^*) e_b, \quad (3.7)$$

and similarly for the other four possibilities above.

4 Octonionic spinors in $D = 11$

In $D = 11$ the Majorana spinor may be written as a 32-component real column vector. However, if we consider \mathbb{R}^{32} as the tensor product $\mathbb{R}^4 \otimes \mathbb{R}^8 \cong \mathbb{R}^4 \otimes \mathbb{O}$ then we can write this as a 4-component octonionic column vector

$$\lambda = \begin{pmatrix} \lambda_1 \\ \lambda_2 \\ \lambda_3 \\ \lambda_4 \end{pmatrix}, \quad \lambda_\alpha \in \mathbb{O}, \quad \alpha = 1, 2, 3, 4. \quad (4.1)$$

A natural set of generators $\{\gamma^M\} = \{\gamma^0, \gamma^{a+1}, \gamma^9, \gamma^{10}\}$, $M = 0, 1, \dots, 10$ for the 4×4 octonionic Clifford algebra is then given by

$$\begin{aligned} \gamma^0 &= \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{pmatrix}, & \gamma^{a+1} &= \begin{pmatrix} 0 & 0 & 0 & e_a^* \\ 0 & 0 & e_a & 0 \\ 0 & e_a^* & 0 & 0 \\ e_a & 0 & 0 & 0 \end{pmatrix}, \\ \gamma^9 &= \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{pmatrix}, & \gamma^{10} &= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}, \end{aligned} \quad (4.2)$$

with $a = 0, 1, \dots, 7$. These matrices satisfy

$$\gamma^M \gamma^N + \gamma^N \gamma^M = 2\eta^{MN} \mathbf{1}, \quad (4.3)$$

and the infinitesimal Lorentz transformation of the spinor λ is

$$\delta\lambda = \frac{1}{4} \omega_{MN} \gamma^M (\gamma^N \lambda), \quad (4.4)$$

where $\omega_{MN} = -\omega_{NM}$. In general, the action of the rank r Clifford algebra element on λ can be written

$$\gamma^{[M_1} \left(\gamma^{M_2} \left(\dots \left(\gamma^{M_{r-1}} \left(\gamma^{M_r} \lambda \right) \right) \dots \right) \right). \quad (4.5)$$

The positioning of the brackets in the above expression follows from repeated application of (2.7); non-associativity matters only for the imaginary gamma matrices γ^{i+1} , which provide a representation of the $\text{SO}(7)$ Clifford algebra. If we define an operator $\hat{\gamma}^M$, whose action is left-multiplication by γ^M , then we can think of the rank r Clifford algebra element as the operator

$$\hat{\gamma}^{[M_1 M_2 \dots M_r]} \equiv \hat{\gamma}^{[M_1} \hat{\gamma}^{M_2} \dots \hat{\gamma}^{M_r]}, \quad (4.6)$$

where the operators $\hat{\gamma}^M$ must be composed as

$$\hat{\gamma}^M \hat{\gamma}^N \lambda = \gamma^M (\gamma^N \lambda) \neq (\gamma^M \gamma^N) \lambda. \quad (4.7)$$

This ensures that the action of $\hat{\gamma}^{[M_1 M_2 \dots M_r]}$ on a spinor is given by (4.5), as required.

5 The octonionic M-algebra

The anti-commutator of two supercharges in the $D = 11$ supergravity theory is conventionally written as the ‘M-algebra’ [18, 19]

$$\{Q_{\bar{\alpha}}, Q_{\bar{\beta}}\} = (\gamma^M C)_{\bar{\alpha}\bar{\beta}} P_M + (\gamma^{MN} C)_{\bar{\alpha}\bar{\beta}} Z_{MN} + (\gamma^{MNPQR} C)_{\bar{\alpha}\bar{\beta}} Z_{MNPQR}, \quad (5.1)$$

where $\bar{\alpha}, \bar{\beta} = 1, \dots, 32$, P_M is the generator of translations and Z_{MN} and Z_{MNPQR} are the brane charges. The charge conjugation matrix $C_{\bar{\alpha}\bar{\beta}}$ serves to lower an index on each of the gamma matrices.

The left-hand side is a symmetric 32×32 matrix with 528 components, while the terms on the right-hand side consist of the rank 1, 2 and 5 Clifford algebra elements, which form a basis for such symmetric matrices. In terms of $SO(1, 10)$ representations:

$$(\mathbf{32} \times \mathbf{32})_{\text{Sym}} = \mathbf{11} + \mathbf{55} + \mathbf{462}. \quad (5.2)$$

We would like to write this algebra in terms of 4×4 octonionic matrices. However, the space of octonionic 4×4 matrices is of dimension $16 \times 8 = 128$, and hence naively does not carry nearly enough degrees of freedom to write (5.1).

The solution to this problem is to use the octonionic Clifford algebra operators $\hat{\gamma}^{[M_1 M_2 \dots M_r]}$ defined in the previous section. These operators (including all ranks r) span a space of dimension $32 \times 32 = 1024$. In other words, their octonionic matrix elements are

$$\langle e_a | \hat{\gamma}^M_{\alpha}{}^{\beta} e_b \rangle = \gamma^M_{\alpha\alpha}{}^{\beta b}, \quad \alpha, \beta = 1, 2, 3, 4, \quad (5.3)$$

and if we think of $\alpha\alpha$ as a composite spinor index $\bar{\alpha} = 1, \dots, 32$, then the set of $\{\gamma^M_{\bar{\alpha}}{}^{\bar{\beta}}\}$ generates the usual real Clifford algebra as in (5.1).

For the charge conjugation matrix, we define the 4×4 real matrix (which is numerically equal to γ^0 but with a different index structure)

$$C_{\alpha\beta} = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{pmatrix}. \quad (5.4)$$

The octonionic matrix elements of this are then trivially

$$C_{\alpha\alpha\beta b} = \langle e_a | C_{\alpha\beta} e_b \rangle = C_{\alpha\beta} \delta_{ab}, \quad (5.5)$$

which can be identified with the 32×32 matrix:

$$C_{\bar{\alpha}\bar{\beta}} = C_{\alpha\alpha\beta b} = C_{\alpha\beta} \delta_{ab}. \quad (5.6)$$

Armed with these tools, the right-hand side can then be written over \mathbb{O} simply by replacing $\bar{\alpha} \rightarrow \alpha$ and putting hats on the gammas:

$$(\hat{\gamma}^M C)_{\alpha\beta} P_M + (\hat{\gamma}^{MN} C)_{\alpha\beta} Z_{MN} + (\hat{\gamma}^{MNPQR} C)_{\alpha\beta} Z_{MNPQR}. \quad (5.7)$$

With the identification $\bar{\alpha} = \alpha a$ we can also write the left-hand side of (5.1) in terms of the composite indices:

$$\{Q_{\bar{\alpha}}, Q_{\bar{\beta}}\} = \{Q_{\alpha a}, Q_{\beta b}\}. \quad (5.8)$$

Now, the expression (5.7) is an octonionic operator with matrix elements as on the right-hand side of (5.1), so on the left we require an octonionic operator

$$\{\widehat{Q_{\alpha}}, \widehat{Q_{\beta}}\} \quad (5.9)$$

with matrix elements given by (5.8). The required operator is obtained simply by contracting (5.8) with the outer product $e_a \times e_b$ defined in (3.5):

$$\{\widehat{Q_{\alpha}}, \widehat{Q_{\beta}}\} \equiv \{Q_{\alpha a}, Q_{\beta b}\} e_a \times e_b. \quad (5.10)$$

The octonionic formulation of the M-algebra is then

$$\{\widehat{Q_{\alpha}}, \widehat{Q_{\beta}}\} = (\hat{\gamma}^M C)_{\alpha\beta} P_M + (\hat{\gamma}^{MN} C)_{\alpha\beta} Z_{MN} + (\hat{\gamma}^{MNPQR} C)_{\alpha\beta} Z_{MNPQR}. \quad (5.11)$$

Using the first two versions of the outer product given in (3.6), we could write the left-hand side as

$$\{\widehat{Q_{\alpha}}, \widehat{Q_{\beta}}\} = \frac{1}{2} \left((Q_{\alpha} Q_{\beta}^*)(\cdot) + (\cdot)(Q_{\beta}^* Q_{\alpha}) + (Q_{\alpha}(\cdot)^*) Q_{\beta} + Q_{\beta}((\cdot)^* Q_{\alpha}) \right). \quad (5.12)$$

The first two terms look similar to the more intuitive anti-commutator $\{Q_{\alpha}, Q_{\beta}^*\}$, explored in [15], but to reproduce the full M-algebra we require all four terms above.

6 Relation to lower dimensions

It is interesting to consider the octonionic version of the supersymmetry algebra after an $\mathbf{11} = \mathbf{4} + \mathbf{7}$ split:

$$\mathrm{SO}(1, 10) \supset \mathrm{SO}(1, 3) \times \mathrm{SO}(7). \quad (6.1)$$

Seven of the Clifford algebra generators γ^{i+1} are imaginary, while the other four are real. This suggests that we split the dimensions as follows:

$$\begin{aligned} M = 0, 1, \dots, 10 & \rightarrow i + 1 = 1, \dots, 8, \\ \mu & = 0, 1, 9, 10. \end{aligned} \quad (6.2)$$

In $D = 4$ we regard the $D = 11$ octonionic spinor $Q_{\alpha a} e_a$ as eight 4-component Majorana spinors $Q_{\alpha a}$, which we may leave packaged as an ‘internal’ octonion. This transforms as the spinor $\mathbf{8}$ of $\mathrm{SO}(7)$. The $D = 4$ interpretation of the octonionic gamma matrices is as follows:

$$\hat{\gamma}_{i+1} = \gamma_* \hat{e}_i, \quad (6.3)$$

$D \setminus \mathcal{N}$	1	2	4	8
11	\mathbb{O}^4			
7	\mathbb{H}^4	\mathbb{O}^4		
5	\mathbb{C}^4	\mathbb{H}^4	\mathbb{O}^4	
4	\mathbb{R}^4	\mathbb{C}^4	\mathbb{H}^4	\mathbb{O}^4

Table 1. A summary of the division algebraic parameterisation of spinors used in $D = n + 3$ supersymmetry algebras. Note that supersymmetry algebras sharing the same \mathbb{A} are equivalent and that Cayley-Dickson doubling \mathbb{A} corresponds to doubling \mathcal{N} , or equivalently climbing upwards in dimension D .

where \hat{e}_i denotes the operator whose action is left-multiplication by e_i and γ_* (otherwise known as γ_5) is the highest rank Clifford element:

$$\gamma_* = -\gamma^0 \gamma^1 \gamma^9 \gamma^{10} = \begin{pmatrix} 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}. \quad (6.4)$$

The matrix $C_{\alpha\beta}$ is just the charge conjugation matrix in $D = 4$.

We do not split the M, N indices of equation (5.11) into μ and i parts here, as the expression of the right-hand side itself is not particularly illuminating. The result is a copy of the $\mathcal{N} = 8$ supersymmetry algebra written over the octonions. The interesting point is that the $D = 11$ supersymmetry algebra *can* be reinterpreted as an octonionic $D = 4$ algebra.

More generally, the spinor and associated gamma matrices defined in (4.1) and (4.2) correspond to those of $D = 4, 5, 7$ if we replace \mathbb{O} with $\mathbb{R}, \mathbb{C}, \mathbb{H}$, respectively — see table 1. This means that in this framework the minimal supersymmetry algebra in these dimensions is written over $\mathbb{R}, \mathbb{C}, \mathbb{H}$, while doubling the amount of supersymmetry corresponds to Cayley-Dickson doubling the division algebra. This process terminates when we reach maximal supersymmetry, i.e. when the Cayley-Dickson process takes us to \mathbb{O} , the largest normed division algebra.

The above discussion serves to emphasise the correspondence between the octonions and maximal supersymmetry in various dimensions. Rather than thinking of the M-theory algebra as an eleven-dimensional real algebra, it may be fruitful to think of it as a four-dimensional octonionic one, as in table 2.

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$D \setminus \mathcal{N}$	1	2	4	8
11	\mathbb{R}^{32}			
7	\mathbb{R}^{16}	\mathbb{C}^{16}		
5	\mathbb{R}^8	\mathbb{C}^8	\mathbb{H}^8	
4	\mathbb{R}^4	\mathbb{C}^4	\mathbb{H}^4	\mathbb{O}^4

Table 2. An alternative parameterisation of spinors used in $D = n + 3$ supersymmetry algebras. From this point of view the octonions single out $D = 4$.

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